

Optimisation : Barycentre

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LISTIC

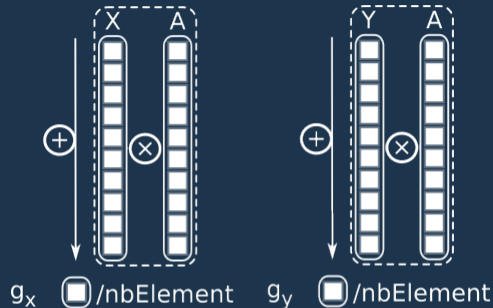


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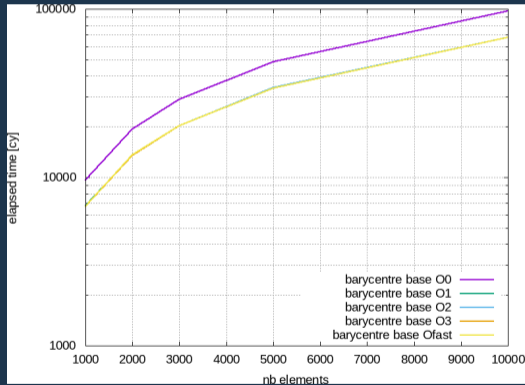
The Barycentre 2d

$$(g_x, g_y) = \frac{1}{N} \sum_{i=1}^N (x_i, y_i) \cdot a_i$$

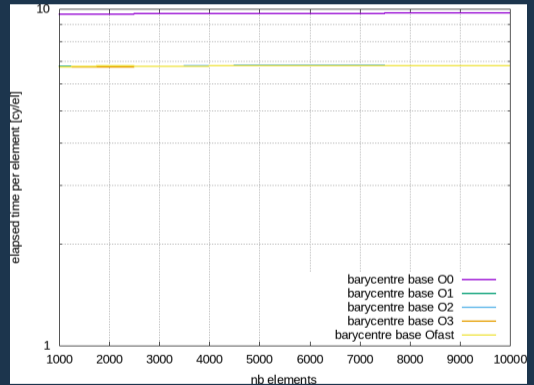


```
void barycentre(float & gx, float & gy, const float * tabX, const float* tabY, const float* tabA, long unsigned int nbElement){
>>  gx = 0.0f;
>>  gy = 0.0f;
>>  for(long unsigned int i(0lu); i < nbElement; ++i){
>>      gx += tabX[i]*tabA[i];
>>      gy += tabY[i]*tabA[i];
>>  }
>>  gx /= (float)nbElement;
>>  gy /= (float)nbElement;
}
```

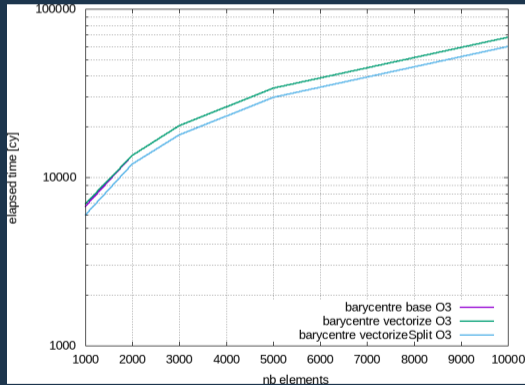
Total Elapsed Time (cy)



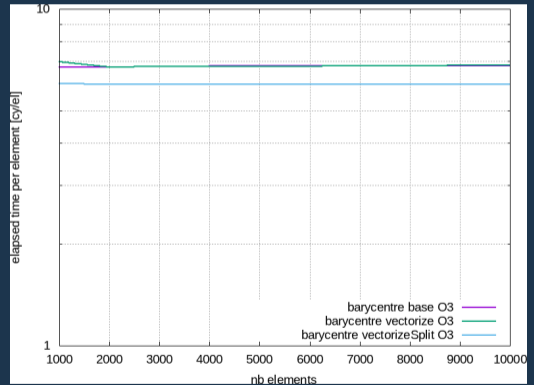
Elapsed Time per element (cy/el)



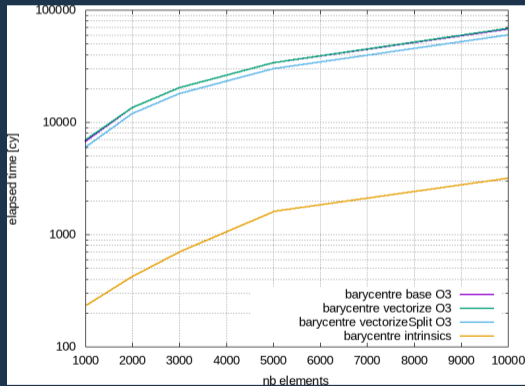
Total Elapsed Time (cy)



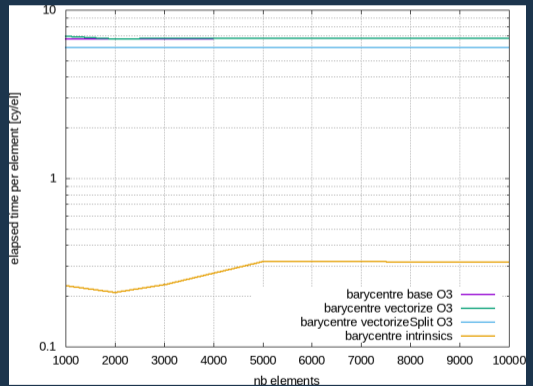
Elapsed Time per element (cy/el)



Total Elapsed Time (cy)

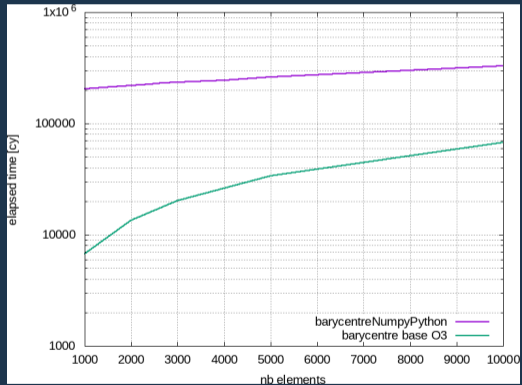


Elapsed Time per element (cy/el)

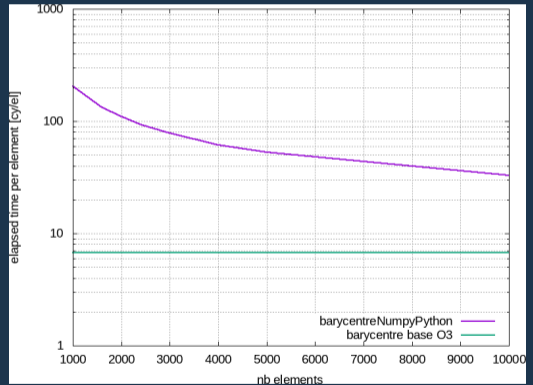


2000 elements, Intrinsics is **28** times faster than -Ofast vectorized

Total Elapsed Time (cy)



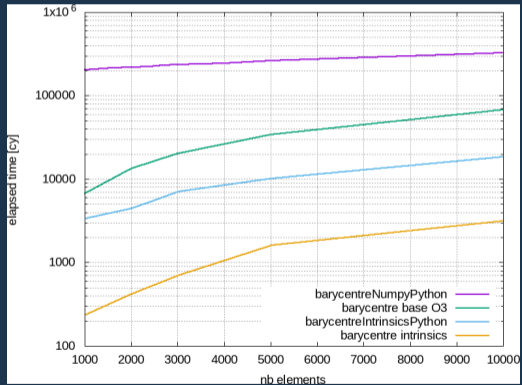
Elapsed Time per element (cy/el)



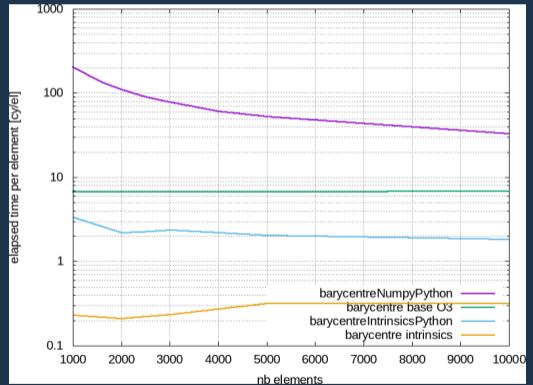
1000 elements, C++ O3 version is **5.7** times faster than **numpy** version



Total Elapsed Time (cy)



Elapsed Time per element (cy/el)



1000 elements, our python version is **53** times faster than **numpy** version